



Measuring



Positioning

IKS8

Magnetic Sensing Head

- Linear Applications
- Rotational Applications

Areas of Application

Industrial Goods

Automation

Life Science

High-Tech Industry

Features

- Non-contact, quick position measurement
- Precise
- Programmable with PC or App
- Single piece unit
- Freely programmable resolutions
- Customisable output frequencies
- A variety of connectors with adaptable cable lengths
- No wear from usage
- High measuring distance tolerance
- Resistant to dust, cooling lubricant emulsion, oil, etc.
- Unlimited measuring length

Measuring movements with the IKS8
Simple – precise – economic

Features

Resolution	0.5 μm to 625 μm, depending on the pole length (see Table 1)
Max. Speed	up to 75 m/s, depending on the pole length and resolution
Energy Consumption (without Load)	65 mA ± 5 % (U _B = 5 V)
Operating Temperature	-20° ... +70° C
Storage Temperature	-20° ... +80° C
Protection Class	IP67

LED	Error displayed when distance or speed too high
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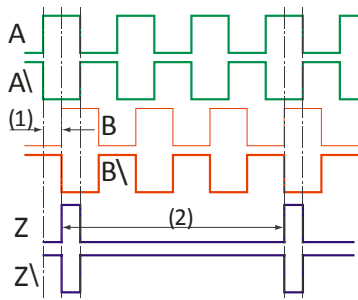
Adjustable Parameters	Resolution, maximum output frequency and counting (with optional programming device and the appropriate software)
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Sensing Head Variants

Pole Length	1 mm, 2 mm, 5 mm
Reference	Reference chip for 2nd track or periodically from the pole pitch
Voltage	5 V or 7 - 32 V
Interface	RS422, Push-Pull TTL, Push-Pull HTL
Cable Length of Sensing Head	Standard 2 m, optional variable length up to 6 m
Connector	open cable end, optional plug according to order code, other specifications on request

Output Signals

Signals	A, A\, B, B\, Z, Z\ 1. RS422 (± 5 V)
Signal Amplitude	2. Push-Pull TTL (+ 5 V) 3. Push-Pull HTL (=U _B - 1 V)



- (1) Phase shift A and B 90° ±10° electrical
- (2) Signal period depending on the reference track pattern or as a periodic reference depending on the pole pitch

Resolution and Speed

Default Values at Output Frequency F = 1000 kHz

Pole Pitch P [mm]	Resolution R [μm]	Speed [m/s]
1	0.5	2
2	1	4
5	2.5	10

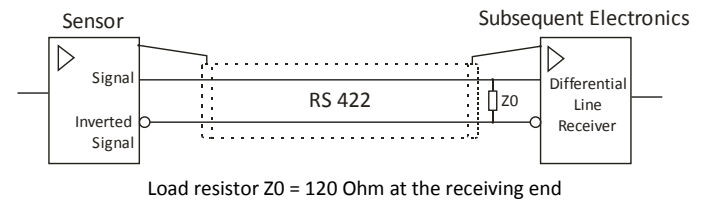
Further Selection (Optional Ordering Parameters)

Pole Pitch P [mm]	Resolution R [μm]	Maximum Output Frequency F [kHz]							
		3500	1500	1000	500	100	50	10	
		Speed [m/s]							
x	625	>75	>75	>75	>75	>75	>75	>75	25
x	312.5	>75	>75	>75	>75	>75	>75	62.5	12.5
x	250	>75	>75	>75	>75	>75	>75	50	10
x	200	>75	>75	>75	>75	>75	>75	40	8
x x x	125	>75	>75	>75	>75	50	25	5	5
x	100	>75	>75	>75	>75	40	20	4	4
x	80	>75	>75	>75	>75	32	16	3.2	3.2
x x x	62.5	>75	>75	>75	>75	25	12.5	2.5	2.5
x x x	50	>75	>75	>75	>75	20	10	2	2
x x x	40	>75	>75	>75	>75	16	8	1.6	1.6
x x x	25	>75	>75	>75	50	10	5	1	1
x x x	20	>75	>75	>75	40	8	4	0.8	0.8
x	16	>75	>75	64	32	6.4	3.2	0.64	0.64
x x x	12.5	>75	75	50	25	5	2.5	0.5	0.5
x x x	10	>75	60	40	20	4	2	0.4	0.4
x x	8	>75	48	32	16	3.2	1.6	0.32	0.32
x x x	5	70	30	20	10	2	1	0.2	0.2
x x	4	56	24	16	8	1.6	0.8	0.16	0.16
x x x	2.5	35	15	10	5	1	0.5	0.1	0.1
x x	2	28	12	8	4	0.8	0.4	0.08	0.08
x x	1	14	6	4	2	0.4	0.2	0.04	0.04
x	0.5	7	3	2	1	0.2	0.1	0.02	0.02

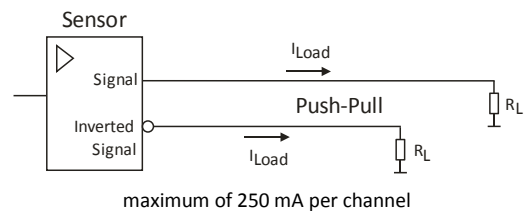
Table 1: Maximum output frequency and speed as a function of pole pitch and resolution

Output Circuit

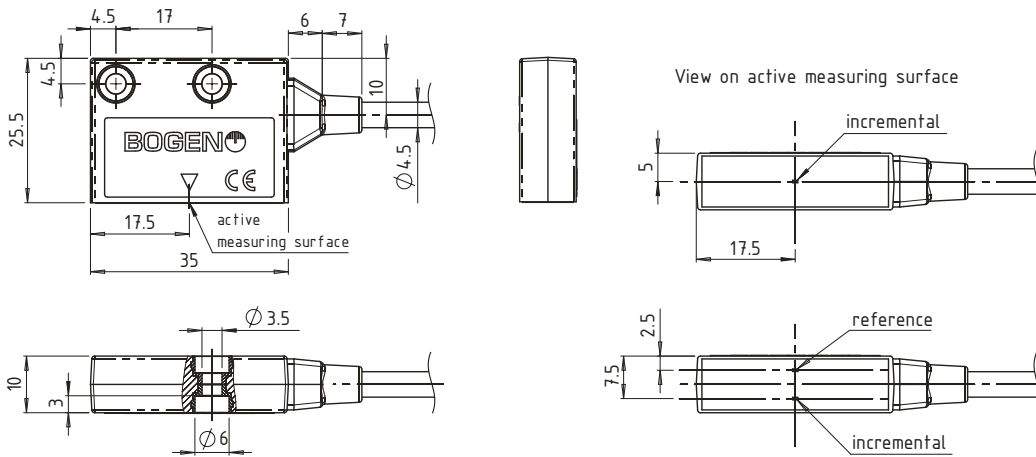
RS422



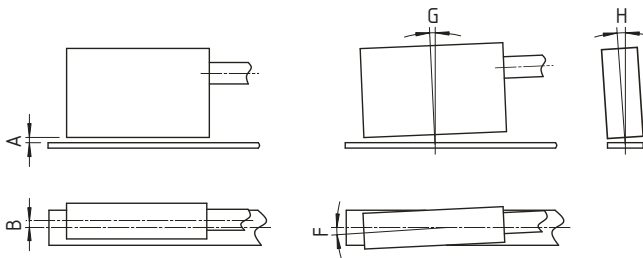
Push-Pull (TTL, HTL)



Dimensions



Installation Tolerances



	Pole Pitch 1 mm	Pole Pitch 2 mm	Pole Pitch 5 mm
A	0.1 ... 0.5 mm	0.1 ... 1.0 mm	0.1 ... 2.5 mm
B ⁽³⁾	2.5 mm	2.5 mm	2.5 mm
B ⁽⁴⁾	0.5 mm	0.5 mm	0.5 mm
G	1°	1°	1°
H	3°	3°	3°
F	3°	3°	3°

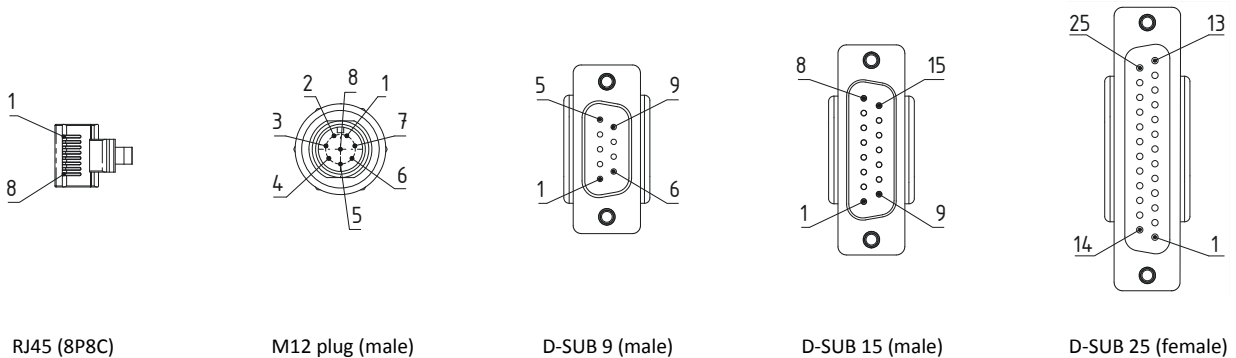
(3) relative to 10 mm scale width (1-track)
 (4) relative to 10 mm scale width (2-track)

Pin Assignment

Signal	Signal *)	Color	Pin No.				
			RJ45	M12 plug (male)	D-SUB 9 (male)	D-SUB 15 (male)	D-SUB 25 (female)
V-	V-	blue	1	1	9	2	1 + 17 **)
V+	V+	red	2	2	5	7	2 + 16 **)
A	A	brown	3	3	4	14	3
A\	A\	green	4	4	8	6	4
B	B	grey	5	5	3	13	6
B\	B\	yellow	6	6	7	5	7
N.C.	Z	pink	7	7	2	12	17
N.C.	Z\	white	8	8	6	4	18
Shield	Shield	-	-	Case	Case	Case	Case

*) Applies to sensing heads with reference signal, ordering code Z1 (periodic index signal) or Z2 (from reference marks).

***) PIN 1 with Pin 17 and Pin 2 with Pin 16 connected through solder bridge



Order Code

Basic Parameters
(required)Optional Parameters
(only necessary if differing from standard)

IKS8 – Z P V D L – R F C

			Code	Explanation
Basic Parameters	Z	Reference Signal	Z0	without
			Z1	periodic index signal, from the pole pitch (standard)
			Z2	from reference marks (requires 2-track magnetic tape with incremental track and reference track)
	P	Pole Pitch [mm]	P1	1 mm
			P2	2 mm
			P5	5 mm
	V	Voltage [V]	V5	5 V
			V732	7...32 V
	D	Interface	D1	RS422
			D2	Push-Pull HTL
			D3	Push-Pull TTL
	L	Cable Length [m]	L1	1 m
			L2	2 m (standard length)
			L3	3 m
...			...	
L6			6 m	
Optional Parameters	R	Resolution [µm]	R0.5	standard for pole pitch 1 mm
			R1	standard for pole pitch 2 mm
			R2.5	standard for pole pitch 5 mm
				Other non-standard resolutions, see section "Resolution and Speed" in Table 1.
	F	Maximum Output Frequency [kHz]	F1000	standard
				Other non-standard output frequencies, see section "Resolution and Speed" in Table 1.
	C	Connector	C1	RJ45 Plug
			C2	M12 plug (male)
			C3	D-SUB 9 (male)
C4			D-SUB 15 (male)	
C5			D-SUB 25 (female)	

Order Example

IKS8-Z1P1V5D1L2

IKS8 Magnetic Sensing Head with periodic index signal, 1 mm pole pitch, voltage 5 V, interface RS422, cable length 2 m
without selected options = standard values:
 0.5 µm resolution, max. output frequency 50 kHz, without connector (open cable end)

IKS8-Z2P2V732D3L5-R125F1000C2

IKS8 Magnetic Sensing Head with reference signal from reference marks (2-track magnetic tape), 2 mm pole pitch, voltage 7 – 32 V (broad-range), interface Push-Pull TTL, cable length 5 m
selected options:
 125 µm resolution, max. output frequency 1000 kHz, M12 plug